




ENHANCING INDOOR LOCALIZATION ESTIMATION USING RSS SIMILARITY- BASED *K*-NEAREST NEIGHBORS

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Overview

- Introduction
- Related Work
- Dataset
- Methodology
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- Conclusion



Introduction

- Indoor positioning is crucial for accurate location information in various indoor environments.
- Unlike outdoor GPS, indoor positioning faces challenges due to weak signals indoors.
- Fingerprint-based methods, using Wi-Fi signals, create unique location fingerprints for positioning.
- Machine learning (ML) algorithms like k -nearest neighbors (k -NN) and random forest enhance indoor positioning accuracy.



Related Work

- Existing research addresses GPS software limitations in indoor environments for localization accuracy.
- Various approaches like fingerprinting-based methods and neural networks enhance indoor localization.
- Studies explore k -NN algorithm and custom distance functions to improve indoor positioning.
- Can we create a framework that inherently considers received signal strength (RSS) data and performs well consistently?

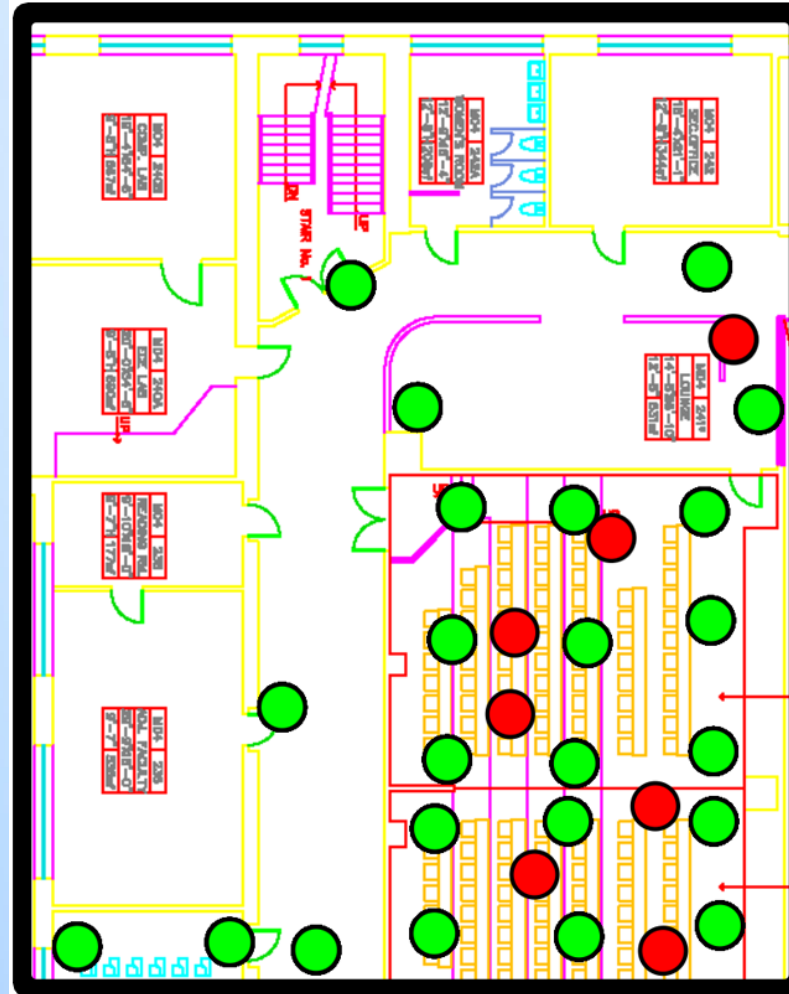


Dataset

- Data collected from engineering building at University of Detroit Mercy across three floors.
- Fingerprints strategically distributed across entire floor area for comprehensive coverage.
- Encompasses diverse settings from small to large classrooms on multiple floors.
- The scope of this research did not address multifloor prediction.



Dataset





Dataset

Table I: AP Information.

xCoord	yCoord	MAC	roomNum
2806	1494	XX:XX:XX :XX:XX:X X	441
2352	1455	XX:XX:XX :XX:XX:X X	441
1959	632	XX:XX:XX :XX:XX:X X	437
2813	873	XX:XX:XX :XX:XX:X X	437

Table II: RSS's mapped to identified APs.

xCoord	yCoord	Floor	AP1	AP2	AP3	AP#
413	94	2	-81	-80	-39	...
531	93	2	-100	-83	-41	...
642	92	2	-85	-86	-46	...

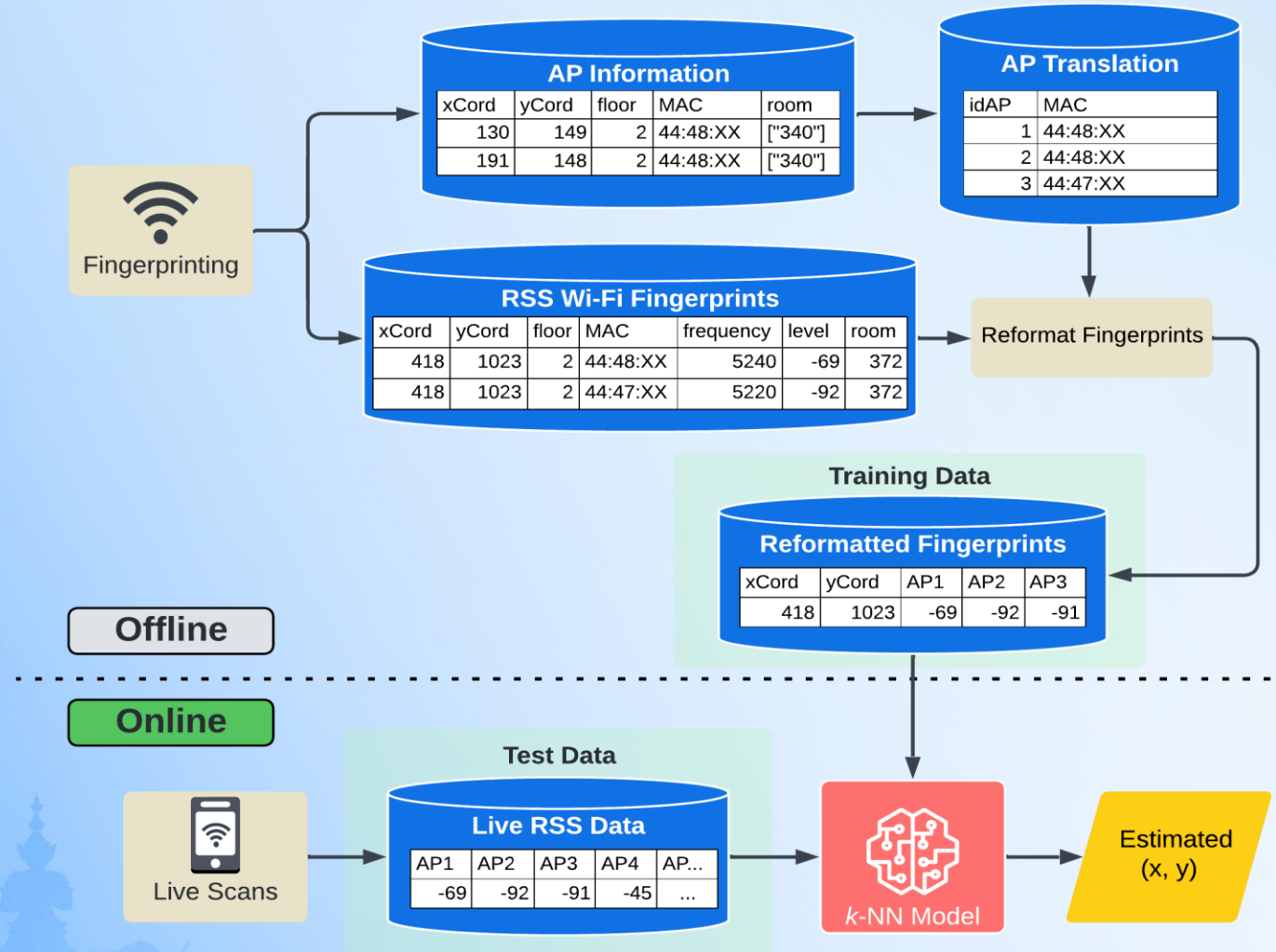


Methodology

- The indoor localization framework consists of offline and online phases for accuracy.
- In the offline phase, data such as access point (AP) positions and RSS levels are collected.
- The online phase involves collecting live Wi-Fi scans for user location estimation.
- The k -NN model is utilized to output an estimated user location.



Methodology





Methodology

- U : test point.
- R_j : training fingerprint reference point.
- Percentile.
- Weighting scheme.

Algorithm 1 RSS Similarity

Require: Two arrays of RSS values from Wi-Fi APs: u and r_j

Ensure: Weighted similarity score between u and r_j

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1: Calculate percentile:  $per = \text{percentiles}((u \cup r_j), [96, 98, 99.5, 100])$ 
2: Initialize empty array:  $rss\_weights = \text{zeros}(\text{dimensions}(u))$ 
3: for  $i \in 0 \dots \text{dimensions}(u) - 1$  do
4:   if  $per_2 \leq u_i \leq per_3$  or  $per_2 \leq r_{ji} \leq per_3$  then
5:      $rss\_weights_i = 1$ 
6:   else if  $per_1 \leq u_i < per_2$  or  $per_1 \leq r_{ji} < per_2$  then
7:      $rss\_weights_i = 0.75$ 
8:   else if  $per_0 \leq u_i < per_1$  or  $per_0 \leq r_{ji} < per_1$  then
9:      $rss\_weights_i = 0.30$ 
10:  else
11:     $rss\_weights_i = 0.15$ 
12:  end if
13: end for
14: Calculate absolute difference:  $rss\_similarity = |u - r_j|$ 

15: Calculate weighted similarity:
 $weighted\_similarity = \sum_{i=0}^{\text{dim}(u)} (rss\_similarity \cdot rss\_weights)$ 
16: return  $weighted\_similarity$ 

```



Results

- RSS similarity outperformed cosine similarity and Euclidean distance functions across multiple floors.
- Weighted distances with $k = 5$ neighbors.
- Results show RSS similarity consistently excelled in R^2 values and MAE.



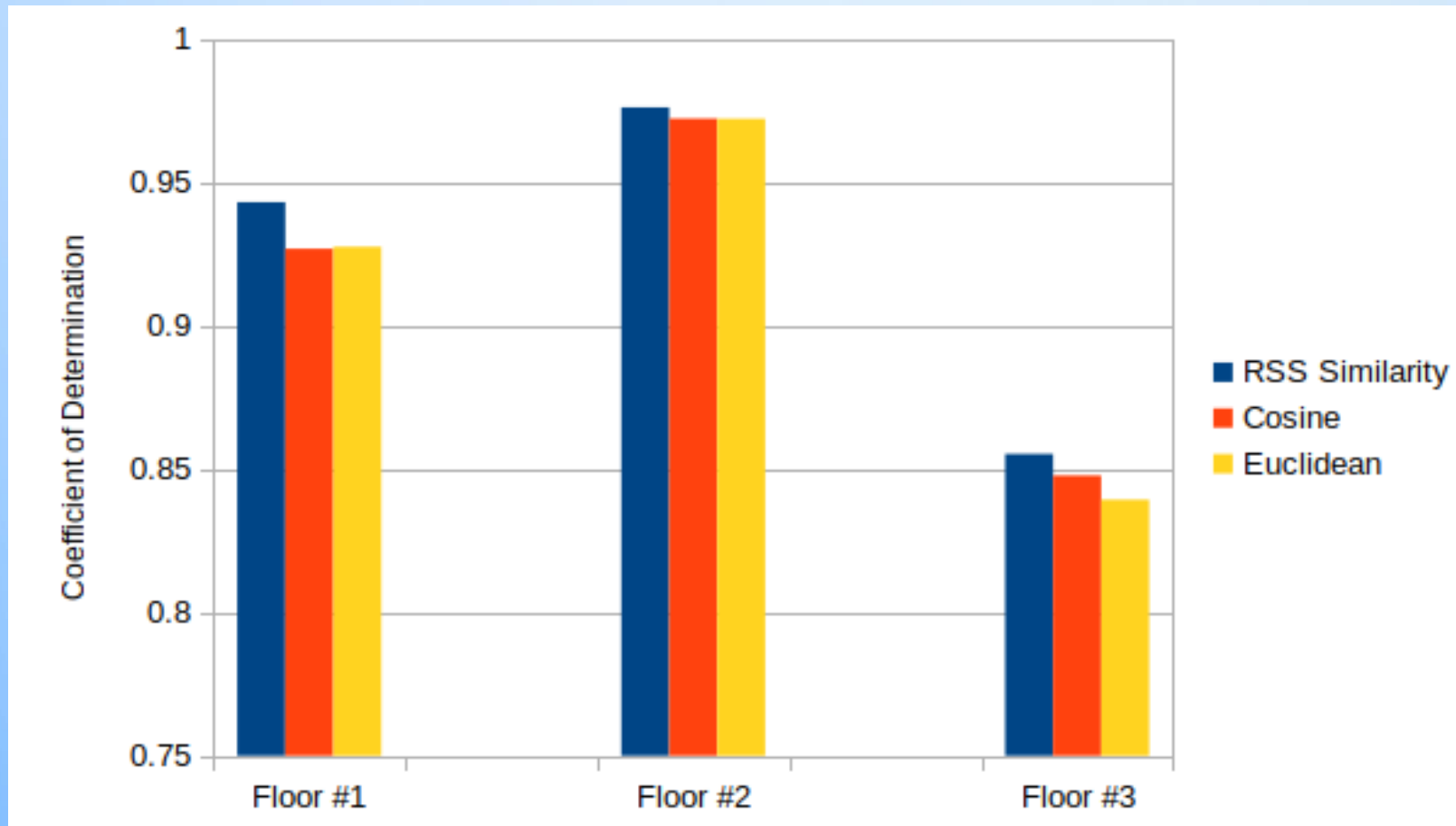
Results

Table III: Comparison of k -NN regressor using different distance functions for different floors.

Floor	F1		F2		F3	
	R ²	MAE	R ²	MAE	R ²	MAE
RSS Similarity	0.94	64	0.98	55	0.86	53
Cosine	0.93	73	0.97	61	0.85	54
Euclidean	0.93	75	0.97	61	0.84	57

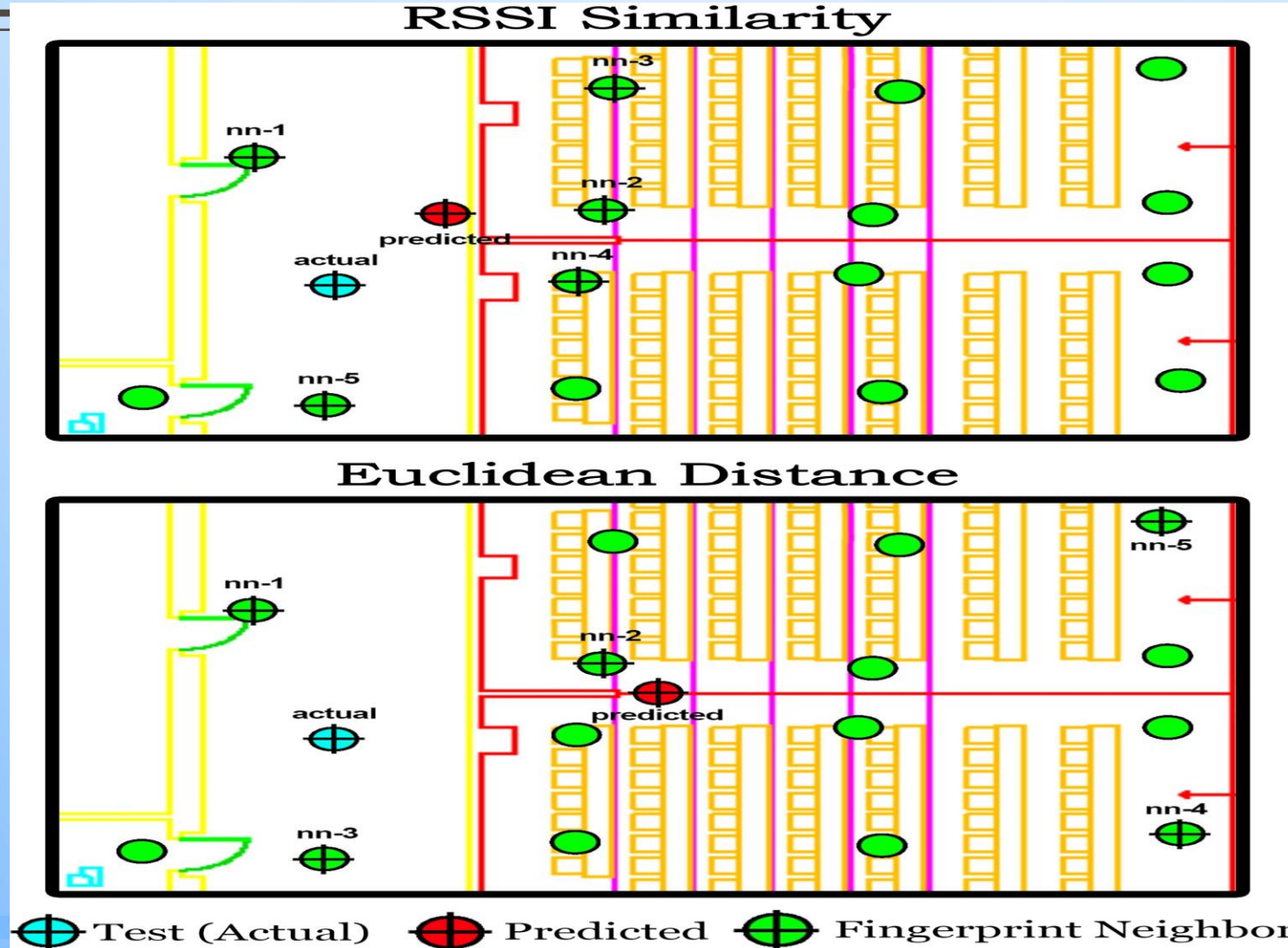


Results





Results





Conclusion

- Achieved enhancement in R^2 score and reduction in distance errors.
- Effectiveness of the proposed approach to fundamentally consider the best fingerprint compared to traditional methods.
- Future work includes strategies to mitigate noisy RSS data and explore alternative algorithms.



Thank you for your time and attention!